

Key extraction from general non-discrete signals

Evgeny Verbitskiy, Pim Tuyls, Chibuzo Obi, Berry Schoenmakers, Boris Škorić

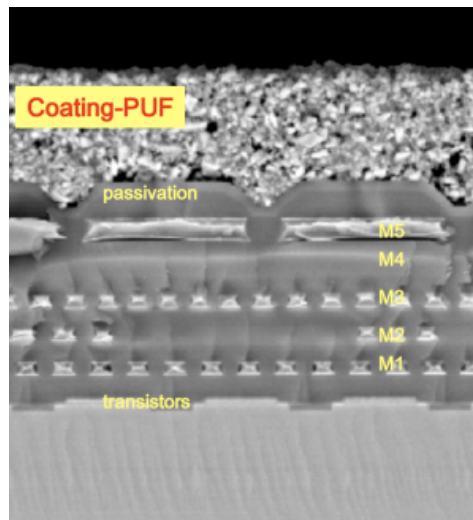
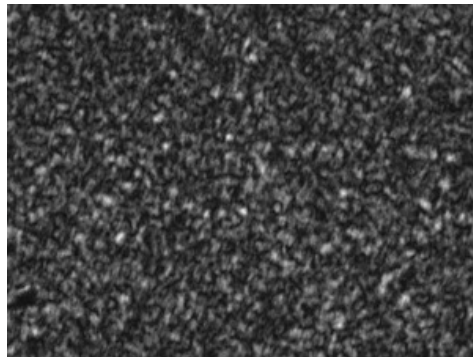
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Outline

- Key extraction from continuous sources
- Defining properties of a Continuous-Source Fuzzy Extractor
- Partitioning scheme
- What if attacker has better knowledge of the source?

Almost all real-life sources generate *real* numbers, not discrete.



Key extraction

- Privacy amplification:

Given a non-uniform source X , derive an L -bit string $f(X)$ as uniformly distributed as possible on $\{0,1\}^L$.

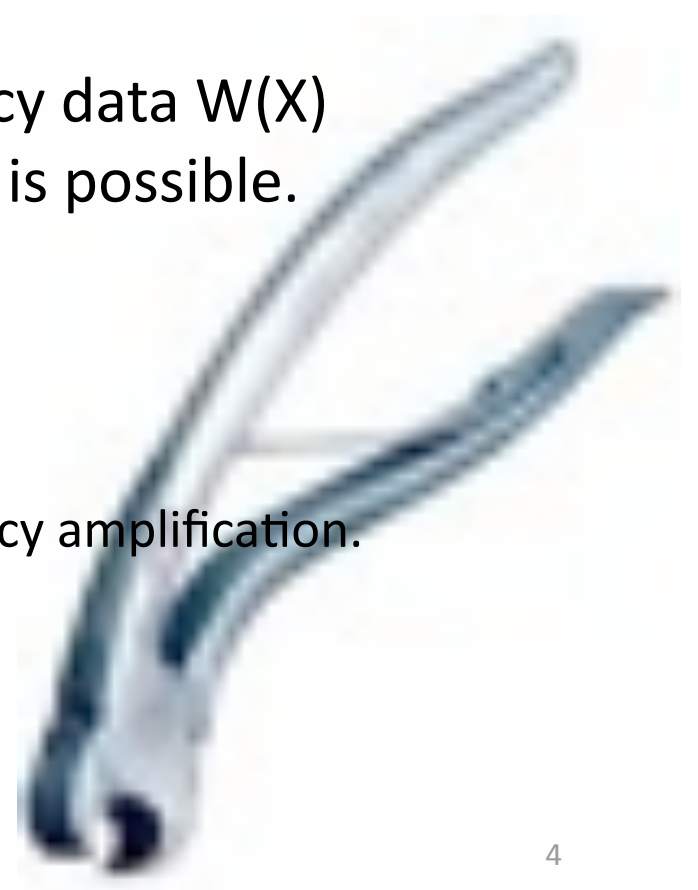
- Information reconciliation:

If the source is noisy, then some redundancy data $W(X)$ must be given before privacy amplification is possible.

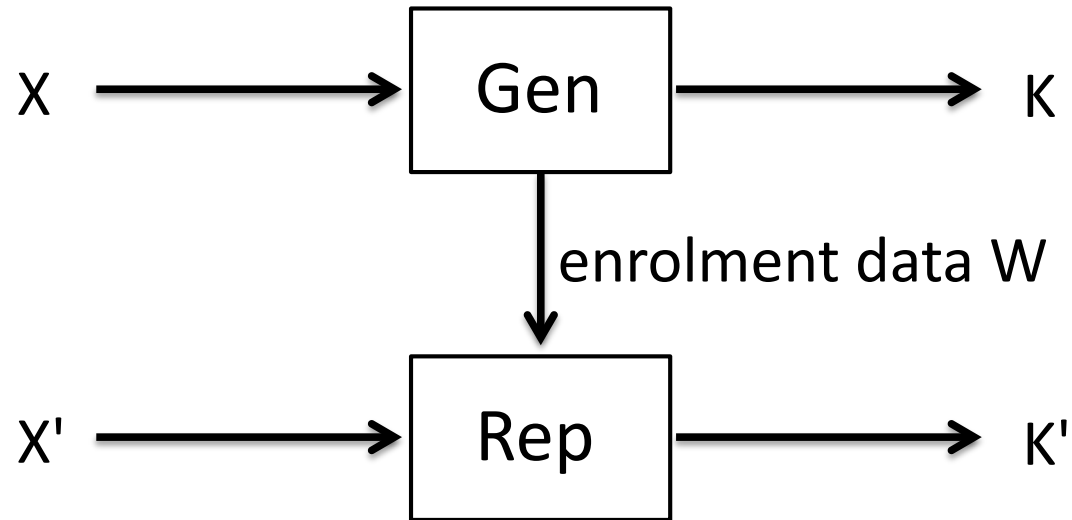
- biometrics
- PUFs

- Fuzzy extractor:

- Does both information reconciliation and privacy amplification.
- Extracts secret key K from noisy source.
- Aims for high entropy $H(K | W)$.



Fuzzy Extractor



Traditionally defined for discrete source X . **But most sources are continuous!**

- extra step: discretization of X
- degree of freedom that can be exploited

We extend the definition [Buhan et al. 2007] of

Continuous-Space Fuzzy Extractor

- Correctness
- Security

[Dodis et al. 2003]

3.2 Fuzzy Extractors

Definition 5. An $(\mathcal{M}, m, \ell, t, \epsilon)$ -fuzzy extractor



avoid

Correctness definitions

Old way

- Requires distance measure
- Hard to see failure prob.

1. t-correct:

If $d(x, x') < t$ then $K' = K$.

2. Worst case ϵ -stochastically noise resilient:

$$\forall x \quad \text{Prob}[\text{Rep}(X', w_x) = k_x] \geq 1 - \epsilon$$

3. On average ϵ -stochastically noise resilient:

For $(k_x, w_x) = \text{Gen}(x)$:

$$\int \text{Prob}[\text{Rep}(X', w_x) = k_x] dx \geq 1 - \epsilon$$

Security definitions

$H_\infty(X)$ not defined
for cont. distribution

1. (m, δ) -secure.

$$H_\infty(X) \geq m \Rightarrow \Delta(KW, U_L W) \leq \delta.$$

2. Worst case m -secure:

$$\forall w \quad H_\infty(K|W=w) \geq m.$$

3. On average m -secure:

$$\tilde{H}_\infty(K|W) \geq m$$

average conditioning

Continuous-Space Fuzzy Extractor: Partitioning scheme

Two nested equiprobable partitions

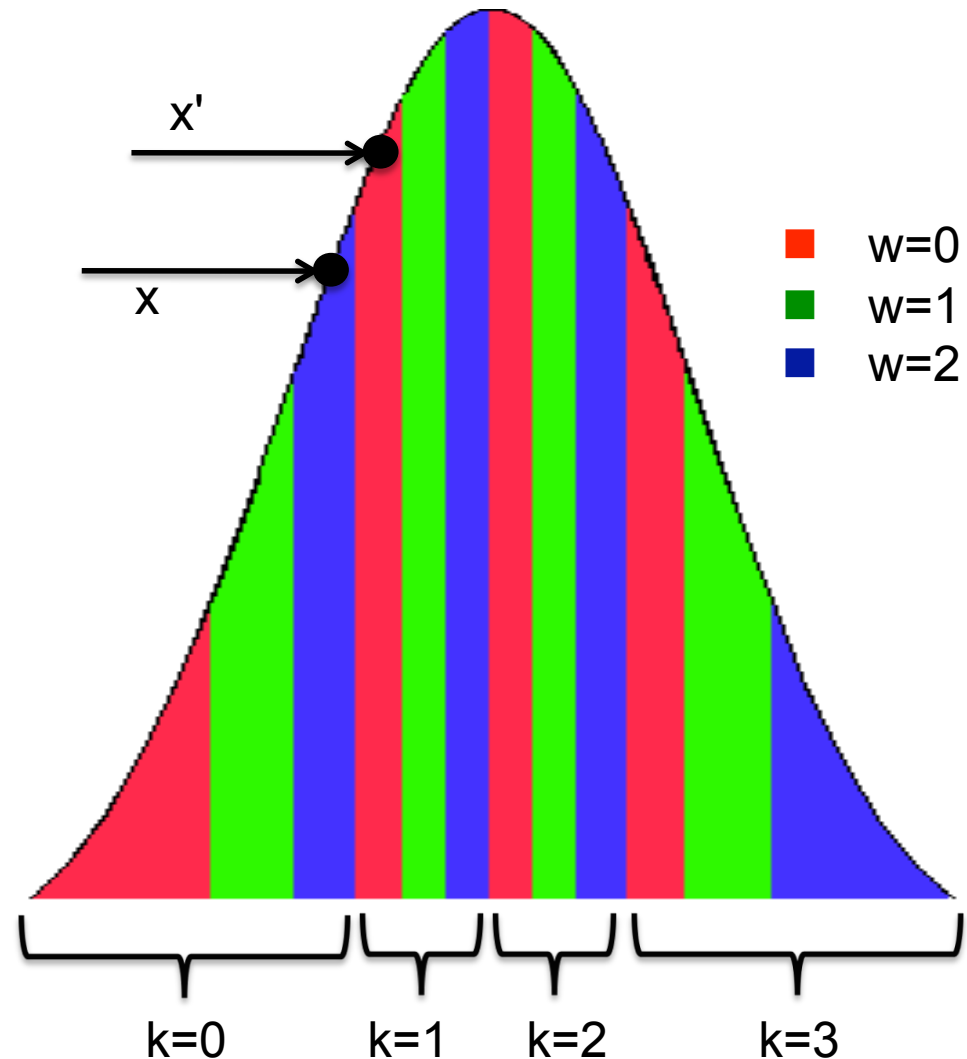
- secret K = outer index
- helper W = inner index

Enrollment

- Measure x .
- $k=0$.
- Store $w=2$.

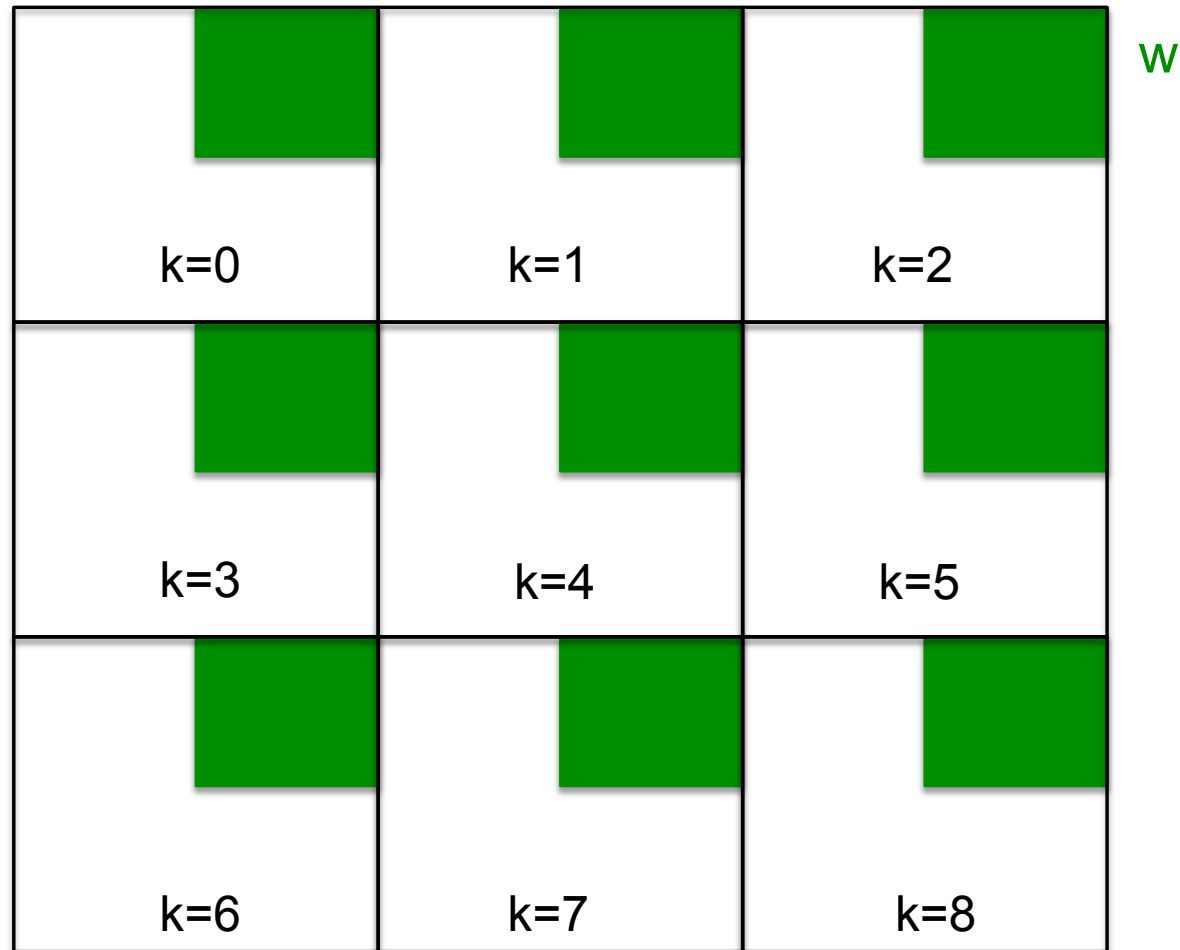
Reconstruction

- Measure x' .
- Read w .
- Go to nearest blue interval.
- Read off $k=0$.



Gap between (k,w) and $(k\pm 1,w)$ reduces noise.

Partitioning scheme: 2D toy example



Gaps between (k,w) and $(k+\Delta k,w)$ reduce noise.

Properties of the partitioning scheme

$K \in \{0,1\}^L$. $W \in \{0,1\}^b$.

- Security of the extracted key K : **$H(K|W) = H(K) = L$.**
 - *Helper data reveals nothing about key.*
 - *Key is uniform.*
 - *"Worst-case L -secure".*
- Leakage about the source X : **$I(X; W) = H(W) = b$.**
 - *Helper data leaks b bits about raw measurement.*
 - *Inevitable!*
- Correctness properties:
 - *depends on specific noise distribution.*

What if source distribution is not known exactly?

Partitioning scheme based on best guess

- Key not exactly uniform
- **Attacker may have better knowledge of X and exploit it!**

Lemma: $\tilde{H}_\infty(K | W) \geq L - \log(1 + \delta 2^{L+b})$

$$\text{with } \delta = \frac{1}{2} \sum_{k,w} \left| \Pr[K = k \wedge W = w] - \frac{1}{2^{L+b}} \right|$$

Gaussian case: $\delta \leq \frac{\sqrt{(\tilde{\sigma} - \sigma)^2 + (\tilde{\mu} - \mu)^2}}{\min(\sigma, \tilde{\sigma})}$

Why average conditioning on W?

Attacker does not control the helper data.

Conclusions

- **Adapted Fuzzy Extractor definition for non-discrete source**
 - correctness and security properties
 - generalization of [Buhan et al.]
- **Explicit construction for known prob. densities**
 - discretization: exploitable extra degree of freedom
 - nested equiprobable intervals
 - perfectly uniform key
 - noise reduced by gaps between intervals (k,w) and $(k+\Delta k,w)$
- **Effect of incomplete knowledge about source**
 - worst case assumption: attacker has full knowledge
 - average-case conditioning on W
 - derived bound on min-entropy of extracted key